

SEMANTICS OF CONTOUR LINES' SPATIAL RELATION

Tao Wang

Chinese Academy of Surveying and Mapping
Beitaipinglu 16, Haidian, Beijing, China, 100039
wangtao@casm.ac.cn

Abstract

Contour line is a basic method for representing terrain. It has advantages over elevation Grid and TIN on that a group of contour lines can visually convey quantity attributes and undulation information of land surface at the same time. Readers of contour map can capture interested terrain information on global structures and local attributes of landscape efficiently and further manage engineering problems. This characteristic can be utilized to benefit digital terrain analysis, in which most functions depend on Grid and TIN and can barely acquire information adapted to variant scales. However, few numerical models exist which can efficiently acquire full information conveyed by contour lines. Experienced readers can virtually construct a mentally continuous surface from a group of nested contour lines. And high level information is derived from the virtual surface. Researchers recognized that the spatial (neighboring) relation between contour lines is a vital factor for the mental process. Therefore spatial relation need be extracted from contour map. The spatial relation of contour lines is different from that of other geographic features. Contour tree has been investigated by researchers and is used for recording contour lines' spatial relation. However information managed by contour tree is not enough for terrain analysis based on contour lines.

The direction of contour line is important because it can help distinguish interior and exterior of region bounded by it. Then with elevation label of contour lines descending direction of region between two neighboring contour lines can be determined. Direction is an indispensable ingredient of spatial relation of contour lines. There is adjacent relation between two neighboring contour lines, which exists over entire map. We propose that location, elevation and adjacent relation information are primary elements of contour lines' spatial information for digital terrain analysis based on contour.

Locally directional adjacency is employed for extending information recorded in contour tree to a full explanation of semantics of contour lines' spatial relation. In this new model spatial relation of two adjacent contour lines can be classified according to geometric relation, elevation ordinal relation and direction of contour lines, which can facilitate digital terrain analysis of contour. To a contour map, this new model can differentiate seven configurations between contour lines. When one contour line is enclosed by another and both are clockwise or anti-clockwise, they represent one local landform object and have different elevation values. And if one is clockwise and another is anti-clockwise, they represent a crater-like landform and have equal elevation value.

When two adjacent contour lines do not contain each other, they are on two neighboring local landform objects. They may be two pits or peaks or may be one pit and one peak. In order to extend local information to entire map, five properties are deduced from definition of directional adjacency to facilitate analyzing functions on contour lines and help on forming continuous surface of terrain. The basis of them is the consistency of contour lines' direction on elevation dimension and the clearly distinction of spatial relation between contours. Further more quantitative properties are defined based previous research using Delaunay TIN on contour lines.

The proposed directional adjacent relation of contour lines can help distinguish all configurations of contour lines. This new model and properties enrich contents of contour tree. It is especially advantageous in terrain analysis of landforms of planetary as moon or Mars on which craters spread everywhere.

1 Introduction

Terrain is a fundamental factor in various research and engineering problems as hydrology, biology and meteorology (Moore etc, 1991). Contour, Regular Grid and TIN are three basic models representing digital terrain. Terrain contour lines are intersections of terrain surface and geographic planar surfaces of different elevations, on which every points have equal elevation. As 1-dimensional curves, contour lines represent the 3-dimensional landscape on the 2-dimensional space. A group of contour lines bear abundant information on global and local terrain features because they are adaptive to undulation of terrain surface. Clarke etc (1982) believed that contour is a selective, aggressive, random elevation sampling scheme for representing terrain. Quantitative value, such as elevation, slope, aspect, surface curvature and drainage area can be extracted from adjacent contour lines. Object information (Moore etc, 1991), which is vaguer, such as valley, ridge, depression, mountain and structural relation among them can also be derived (Cronin, 1995; Kweon etc, 1994).

In research of digital terrain analysis, there are intensive efforts on finding structural information of topography. Surface network (Wolf, 1991; Brandli, 1996) is a most investigated topic by researchers in order to address abstract representation of terrain, and most of the work is based on Regular Grid DEM (Rana, 2004). Kulik and Egenhofer (2003) designed a qualitative language to describe specific features based on horizons of terrain silhouette. However there are few research efforts on numerical models based on contour lines.

A general GIS database stores location and elevation label for a contour line and uses it mainly for visualization and as data source of Grid and TIN DEM. A lot of terrain analyzing functions does not rely on contour line because it is hard to automatically construct a continuous surface which is visually obvious for human being (Mark, 1997; Cronin, 2000). However, contour lines have advantages over Grid and TIN DEM if contour lines' spatial relation and nesting information, which make it an object-oriented

model, can be provided.

The spatial relation of contour lines is different from that of other geographic feature, which is built up on relation between geometric elements (Egenhofer and Franzosa, 1991). When contour lines are taken as 1-dimensional closed curves, the topological relation can only be 'disjoint' from the point-set based spatial relation model. If inter-contour regions bounded by adjacent contour lines are considered, the relation includes 'contain' and 'disjoint'. Variation of elevation of adjacent contour lines has been noticed by researchers for a long time and contour tree (Morse, 1969) has been used for recording the special spatial relation, which accommodates geometric and ordinal relation. Contour lines and inter-contour region are represented by nodes and edges of contour tree, whose root is the lowest contour lines or lowest inter-contour region. There are three types of algorithms for constructing contour tree: mathematical morphologic-based, polygon-in-polygon test based and TIN (or Voronoi) based (Roubal and Poiker, 1985; Kweon and Kanade, 1995; Cronin, 2000; Wang, 2004; Chen, Qiao and etc, 2004). The work is concentrated on finding enclosure or adjacent relation between contour lines.

However, information on spatial relation between contour lines recorded in contour tree cannot be distinguished completely. When one contour line is enclosed by another on map, the spatial relation of them can be varied according to elevation values of them. But the enclosed one can only be denoted as a branch node of another in contour tree. This paper investigates the formalization of semantics of contour lines' spatial relation and analyzing the spatial configuration of different relation according to both geometric and numeric of contour lines.

2 Directional Adjacency of Contour Lines

Morse (1969) defined adjacent contour lines on a contour map which has not degenerate situation (without cliff or overlapping of other geographic features and annotations):

“Two contour lines are said to be adjacent if a line can be drawn that connects the two contour lines and intersects no other contour lines.”

Morse also noticed that the set of adjacent contour lines of a given contour line can be divided into two subsets: the left set and the right set. In the contour map showed in Figure 1, *a* is spatially adjacent to *b* and *c* and not to *e* and *d*. But according to Morse's definition, each contour line in Figure 1 is adjacent to any others, even they are not geometrically adjacent.

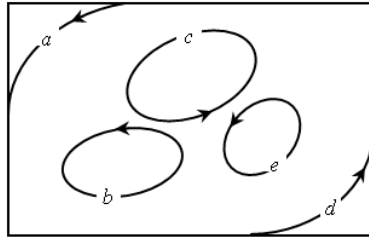


Fig. 1. Adjacency of contour lines.

Previous works on constructing contour tree are all follow Morse's definition implicitly although few mention this in publications. However, most existing algorithm trying to find adjacency information, whether based on mathematical morphologic operators or polygon-in-polygon test, did not extract full set adjacent relation. Wang (2004) and Chen etc (2004) discussed the strategy for deriving all adjacent contour lines based on those acquired by directly searching, but the two subsets and semantics of different configuration are not distinguished further.

In a real contour map, the configuration of contour lines can be very strange, especially at landscape of Karst or Loess. The enclosure relation at saddle area is complicated and it is hard to find enclosure information when boundary of map sheet may break one contour line into several parts. In this situation, refined adjacent relation is helpful for digital terrain analysis.

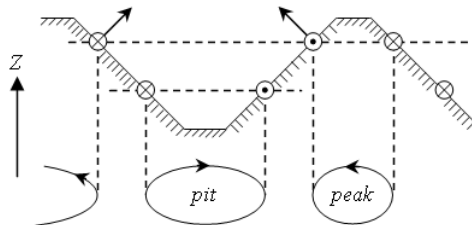


Fig. 2. Elevation and geometric direction of contour lines.

In order to accommodate situation of contour lines at terrace, Morse (1969) defined that when one traverses from one node to successive node on a contour line, if the left side is higher and right is lower, then this contour line is in positive direction. In this way, interior and exterior of region bounded by a contour line can be distinguished. And further, the closed curves of contour lines representing pit is geometrically clockwise and those representing peak is geometrically anti-clockwise on the 2-dimensional plane, as indicated in figure 2. Now contour line has an attribute of directionality, which can be represent by the orientation of contour lines. Digital computational model can find more meaningful information when all contour lines are in consistent direction.

Wang (2004) designed an algorithm for adjusting direction of contour lines into positive.

Assume all contour lines in a given map are processed by this algorithm and given two contour lines c_1 with elevation $H(c_1)$ and c_2 with elevation $H(c_2)$. The elevation interval is dH (there may be more than one dH value in one contour map, but it does not have any effects on directional adjacency).

The definition of adjacent contour line of Morse is followed. If two contour lines c_1 and c_2 are adjacent, we denote it as: $N_{\emptyset}(c_1)=c_2$ and $N_{\emptyset}(c_2)=c_1$.

In order to determine positive direction of a contour line, we must convert Morse's theoretical definition to one which can be implemented. Wang (2004) used Delaunay TIN to adjust direction of contour lines and the strategy can be employed to set an equivalent definition.

Definition. Positive direction of contour line. In the Delaunay TIN on a contour map in which not all contour lines have same elevation, we can find a triangle whose two vertices v_a, v_b are on contour line c_1 and the third v_q on is on contour line c_2 , where v_b is a subsequent node of v_a on c_1 and v_q is on the right of vector $v_a v_b$. If c_1 is higher than c_2 , c_1 is in positive direction.

Definition. Positive adjacent contour line. If c_1 and c_2 are adjacent contour line and c_2 is on the left side of c_1 , c_2 is positive adjacent contour line of c_1 .

If $H(c_2)-H(c_1)>0$, we denote $N_1(c_1)=c_2$
 If $H(c_2)-H(c_1)=0$, we denote $N_{+0}(c_1)=c_2$

Definition. Negative adjacent contour line. If c_1 and c_2 are adjacent contour line and c_2 is on the right side of c_1 , c_2 is negative adjacent contour line of c_1 .

If $H(c_2)-H(c_1)<0$, we denote $N_{-1}(c_1)=c_2$
 If $H(c_2)-H(c_1)=0$, we denote $N_{-0}(c_1)=c_2$

Definition. Directional adjacency. For two given contour lines c_1 and c_2 , directional adjacency is denoted as:

$$N_k(c_1, c_2)=1, k = 1, -1, +0, -0, \emptyset$$

where k is called order of directional adjacency.

Further, a contour line is zero-order adjacent to itself:

$$N_{+0}(c_1, c_1) = N_{-0}(c_1, c_1) = 1$$

3 Spatial Configurations of Directional Adjacency

For convenience, we define a modular function $M(\bullet)$ to distinguish different set of






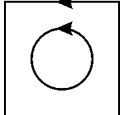
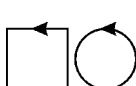
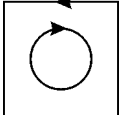

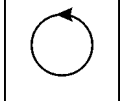


contour lines.

$$\begin{aligned} M(N_{+0}) &= M(N_{-0}) = 0 \\ M(N_1) &= M(N_{-1}) = 1 \\ M(N_\Phi) &= \Phi \end{aligned}$$

When $M(N_k)=p$ ($p=0, 1, \Phi$), the related c_1 and c_2 are called p -order adjacent contour pair. Specially, c_1 and c_2 are not adjacent if $p=\Phi$. We further define sets of contour lines with equal characteristics.

- Set $A_+ = \{c \mid N_k(c_1, c) = 1, k = 1, +0\}$ denotes positive adjacent set of c_1
- Set $A_- = \{c \mid N_k(c_1, c) = 1, k = -1, -0\}$ denotes negative adjacent set of c_1
- Set $A_1 = \{c \mid N_k(c_1, c) = 1, k = 1, -1\}$ denotes 1-order adjacent set of c_1
- Set $A_0 = \{c \mid N_k(c_1, c) = 1, k = +0, -0\}$ denotes 0-order adjacent set of c_1
- Set $A_\Phi = \{c \mid N_k(c_1, c) = 1, k = \Phi\}$ denotes non-adjacent set of c_1
- Set $A_{+1} = A_+ \cap A_1$ denotes 1-order positive adjacent contour lines of c_1
- Set $A_{-1} = A_- \cap A_1$ denotes 1-order negative adjacent set of c_1
- Set $A_{+0} = A_+ \cap A_0$ denotes 0-order positive adjacent set of c_1
- Set $A_{-0} = A_- \cap A_0$ denotes 0-order negative adjacent set of c_1
- Set $A = A_+ \sqcup A_- = A_1 \sqcup A_0 = A_{+1} \sqcup A_{-1} \sqcup A_{-0} \sqcup A_{+0}$ denotes adjacent set of c_1
- Set $C = A \sqcup A_\Phi$ denotes full set of contour lines in the given map

Table 1. Spatial Configurations of Adjacent Contour Lines

		c_2			
$N_k(c_1, c_2)=1$					
					
c_1		(a) $k=1$	(b) $k=-0$	(c) $k=+0$	(d) $k=-1$
					
		(e) $k=-0$	(f) $k=1$	(g) $k=-1$	(h) $k=+0$

Now spatial relation of two adjacent contour lines can be classified according to geometric relation and elevation ordinal relation. Table 1 indicates that, if two adjacent contour lines have not containing relation as showed in (b), (d), (f) and (h), they are on two neighboring local landforms, pit or peak. And they can be further divided into two

types by their elevation ordinal relation. Contour lines in (b) represent two peaks and those in (h) represent two pits. Those in (d) and (f) represent one pit and one peak. Although modular function produces different values, (d) and (f) indicate two equivalent configurations.

If one is enclosed by another and both are clockwise or anti-clockwise as showed in (a) and (g), they represent one local landform and have different elevation values. And if one is clockwise and another is anti-clockwise, they represent a crater-like landform and have equal elevation value.

From definition of directional adjacency, the following five properties can be deduced for application in digital terrain analysis.

- (1) $N_I(c_1, c_2)=1 \Leftrightarrow N_{-I}(c_2, c_1)=1$, that means, $N_I(c_1)=c_2 \Leftrightarrow N_{-I}(c_2)=c_1$ or vice versa $N_{-I}(c_2)=c_1 \Leftrightarrow N_I(c_1)=c_2$
- (2) $N_{-0}(c_1, c_2)=1 \Leftrightarrow N_{-0}(c_2, c_1)=1$, $N_{+0}(c_1, c_2)=1 \Leftrightarrow N_{+0}(c_2, c_1)=1$, that means, $N_{-0}(c_1)=c_2$ (or $N_{+0}(c_1)=c_2$) $\Leftrightarrow N_{-0}(c_2)=c_1$ (or $N_{+0}(c_2)=c_1$)
- (3) $\{N_I(c_1, c_2)=1 \text{ and } N_I(c_1, c_3)=1\} \Rightarrow \{N_{-0}(c_2, c_3)=1, N_{-0}(c_3, c_2)=1\}$, $\{N_{-I}(c_1, c_2)=1 \text{ and } N_{-I}(c_1, c_3)=1\} \Rightarrow \{N_{+0}(c_2, c_3)=1, N_{+0}(c_3, c_2)=1\}$
- (4) $\{N_{+0}(c_1, c_2)=1 \text{ and } N_I(c_1, c_3)=1\} \Rightarrow \{N_I(c_2, c_3)=1\}$, $\{N_{-0}(c_1, c_2)=1 \text{ and } N_{-I}(c_1, c_3)=1\} \Rightarrow \{N_{-I}(c_2, c_3)=1\}$
- (5) $\{N_I(c_1, c_2)=1 \text{ and } N_{-0}(c_2, c_3)=1\} \Rightarrow \{N_I(c_1, c_3)=1\}$, $\{N_{-I}(c_1, c_2)=1 \text{ and } N_{+0}(c_2, c_3)=1\} \Rightarrow \{N_{-I}(c_1, c_3)=1\}$, that means, for contour lines c_1, c_2 and c_3 , if $N_I(c_1)=c_2$, $N_{-0}(c_2)=c_3$, then $N_I(c_1)=c_3$; if $N_{-I}(c_1)=c_2$, $N_{+0}(c_2)=c_3$, then $N_{-I}(c_1)=c_3$. In figure 1, if $N_I(a)=b$, $N_{-0}(b)=e$, then $N_I(a)=e$.

These properties, which extend local information to global, can facilitate analyzing functions on contour lines and help on forming continuous surface of terrain. The basis of them is the consistency of contour lines' direction on elevation dimension and the clearly distinction of spatial relation between contours.

4 Quantitative Aspects of Directional Adjacency

Above sections defined directional adjacency and its properties mostly from qualitative aspects. However digital terrain analysis needs quantitative properties and results. We designed an algorithm for extracting adjacent relation based on Delaunay TIN and defined Valid Node (Wang, 2004). Here more quantitative properties are defined or revised. One edge in TIN is an auxiliary edge if its two end nodes are located on two contour lines.

Definition. Strong Valid Node. If there is an auxiliary edge whose one node P_1 is on contour line c_1 and another on c_2 , P_1 is called valid node of c_2 on c_1 . Further, if P_1 is not valid node of any other contour line at the same side of c_1 with c_2 , P_1 is called strong

valid node.

Definition. **Valid Edge.** If there are two consecutive nodes on c_1 and they are valid nodes of c_2 , the edge bounded by the two nodes is called valid edge.

Definition. **Weak Valid Node.** If a node on c_1 is not valid node of c_2 and any other contour line at the same side of c_1 , it is weak valid node of c_2 on c_1 .

Definition. **Weak Valid Part.** If there are consecutive weak valid nodes of c_2 on c_1 which are bounded by two strong valid nodes of c_2 on c_1 , the part of c_1 which starts from first strong valid node to next one and passes all weak valid nodes is weak valid part of c_2 on c_1 .

Definition. **Degree of Adjacency.** For two given contour lines c_1 with length l and c_2 , if the length of all valid edges and valid parts of c_2 on c_1 is l_v , degree of adjacency of c_1 to c_2 is:

$$D(c_1, c_2) = l_v / l$$

And similarly define degree of adjacency of c_2 to c_1 is $D(c_2, c_1)$. Then degree of adjacency of c_1 and c_2 is:

$$D_{c_1c_2} = \text{Max}(D(c_1, c_2), D(c_2, c_1))$$

Value $D_{c_1c_2}$ varies from 0 to 1. If $N_\phi(c_1, c_2)=1$, $D_{c_1c_2} = 0$. For two adjacent contour lines which are not geometrically proximal, their degree of adjacency can be computed when deriving full set of directional adjacent relation by properties of last section.

5 Conclusions

We extend our previous research and propose that directional adjacent relation of contour lines can help distinguishing every configuration of contour lines. The properties are also analyzed to facilitate further applications. This new model enriches meaning of contour tree. Test work has been implemented and showed more robustness in automatic labeling of real contour map. The direction on elevation dimension is also employed in contour threading from regular elevation grid matrix and produce encouraging result on efficiency (Wang, 2006).

Future work based on directional adjacency can investigate more quantitative properties in geometric and elevation ordinal aspects. These could help digital terrain analysis such as automatic reasoning, terrain feature extracting and landform classification. Distinct semantics of spatial relations of contour lines is also advantageous in terrain analysis of landforms of planetary as moon or Mars on which craters with variant sizes spread everywhere.

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